## ON THE STATE OF STRESS OR A STMP WEAKEIED BY IDENTICAL CTBCULAR TRANSVEASE OPENAGS

PMM Vol. 42, No. 5, 1978, pp. 930-935.<br>N. 1. MIRONENKO<br>(Alma-Ata)<br>(Received July 18, 1977)

The title problem is solved using the Sherman [1] method which makes it possible to reduce the problem in question to an auxilliary problem for a solid strip, a solution for which is obtained with help of the Fourier tranform. The solution of the problem is reduced, in the last stage, to an infinite tystem of linear algebraic equations, and the system is at least quasiregular at arbitrarily small distances from the boundary. A numerical analyst is alwo given for the following three variants of loading of the stap: for longitudinal tension, uniform transverse tension and for uniform preasure along the hole contours.

Let us consider a strip of width $2 a$, weakened by two holes of equal radii $R$, symmetrically distributed in transverse direction, their centers at the distance $2 c$ from each other (Fig. 1). The strip is acted upon by uniform tenile forces $T_{x}$ and


Fig. 1
$T_{y}$ in the longitudinal and transverse direction reapectively. We denote by $S_{0}$ the triply connected region of the strip, and by $S_{1}, S_{2}$ the regions contained within the circles $L_{1}$ and $L_{2}$. The area of the solid strip is $S=S_{0}+S_{1}+S_{2}$. The unknown stresses are conveniently written in the form

$$
X_{x}^{(1)}=T_{x}+X_{x}, \quad Y_{y}^{(1)}=T_{y}+Y_{y}, X_{y}^{(1)}=X_{y}
$$

where $X_{x}, Y_{y}$ and $X_{y}$ represent the result of the perturbation caused by the presence of holes. The Kolotov-Muskhelishvili potentials correaponding to the streases $X_{x}, Y_{y}$ and $X_{y}$ are denoted by $\varphi_{1}(z)$ and $\psi_{1}(z)$. The boundary conditions on the longitudinal boundaries are obvious for the additional stremses $X_{x}, Y_{y}$ and $X_{y}$,
and on the circles $L_{j}(j=1,2)$ they have the form

$$
\begin{aligned}
& \varphi_{1}(t)+\overline{t \varphi_{1}^{\prime}(t)}+\overline{\psi_{1}(t)}=2 h_{1}\left(t-b_{j}\right)+\frac{2 h_{2} R^{2}}{t-b_{j}}+2 C_{j} \\
& \left(h_{1}=-\left(T_{x}+T_{y}\right) / 4, h_{2}=\left(T_{x}-T_{y}\right) / 4, b_{1}=-b_{2}=i c\right)
\end{aligned}
$$

where $C_{j}$ is a constant not affecting the state of stress.
Following [1], we introduce a new unknown function

$$
2 \omega(t)=\varphi_{1}(t)-t \overline{\varphi_{1}^{\prime}(t)}-\overline{\psi_{1}(t)} \text { on } L_{j}, \quad j=1,2
$$

and this enables us to construct the functions $\varphi(z)$ and $\psi(z)$ analytic in the region
$S$, i. e. in the solid strip. In the region $S_{0}$ these functions are given by the formulas

$$
\begin{align*}
& \varphi(z)=\varphi_{1}(z)-\sum_{j=1}^{2}\left(\varphi_{j}^{*}(z)+\frac{h_{2} R^{2}}{z-b_{j}}\right)  \tag{1}\\
& \psi(z)=\psi_{1}(z)-\sum_{j=1}^{2}\left[\psi_{j}^{*}(z)+h_{2} R \sum_{k=2}^{3} \lambda_{j k}\left(\frac{R}{z-b_{j}}\right)^{k}\right] \\
& \varphi_{j}^{*}(z)=\frac{1}{2 \pi i} \int_{L_{j}} \frac{\omega(t) d t}{t-z} \\
& \varphi_{j}^{*}(z)=-\frac{1}{2 \pi i} \int_{L_{j}} \frac{\overline{\omega(t)}+\overline{t \omega^{\prime}}(t)}{t-z} d t \\
& \lambda_{j_{2}}=-b_{j} / R, \quad \lambda_{j s}=1
\end{align*}
$$

The integrals in these and in the following formulas are taken in the clockwise direction.

Let us write the functions $\varphi_{j}{ }^{*}(z)$ and $\psi_{j}{ }^{*}(z)$ for $z$ lying outside $L_{j}$, in the form of series

$$
\begin{align*}
& \varphi_{j}^{*}(z)=-\sum_{k=0}^{\infty} \alpha_{k j}\left(\frac{R}{z-b_{j}}\right)^{k+1}, \quad \psi_{j}^{*}(z)=\sum_{k=0}^{\infty} \beta(1)\left(\frac{R}{z-b_{j}}\right)^{k+1} .  \tag{2}\\
& \beta_{0 j}^{(1)}=-\beta_{0 j}-\bar{\beta}_{0 j} \\
& \beta_{k j}^{(1)}=-\bar{\beta}_{k j}+k \frac{b_{j}}{R} \alpha_{k-1, j}-(k-1) a_{k-2, j}, \quad k \geqslant 1 \\
& \alpha_{k j}=\frac{1}{2 \pi i R^{k+1}} \int_{L_{j}} \omega(t)\left(t-b_{j}\right)^{k} d t, \quad \beta_{k j}=\frac{1}{2 \pi i R^{k+1}} \int_{L_{j}} \omega(t) \overline{\left(t-b_{j}\right)^{k} d t}
\end{align*}
$$

Assuming that $\alpha_{k j}$ and $\beta_{k j}$ are the Fourier coefficients of the function $\omega(t)$ on $L_{1}$ and $L_{2}$ and taking into account the symmetric character of the state of stress relative to both axes, we have $\alpha_{k 2}=\bar{\alpha}_{k 1}, \beta_{k 2}=\bar{\beta}_{k 1}$. When $\dot{k}=0,2,4, \ldots$,
$\alpha_{k j}$ and $\beta_{h j}$ are real, and for $k=1,3,5, \ldots$ they are purely imaginary. The formulas (1) and (2) yield expressions for the potentials $\varphi_{1}(z)$ and $\psi_{1}(z)$ sought, in terms of the functions $\varphi(t)$ and $\psi(t)$ (which have the corresponding state of stress $\left.X_{x}{ }^{(2)}, Y_{y}{ }_{1}{ }^{(2)}, X_{y}{ }^{(2)}\right)$

$$
\begin{align*}
& \varphi_{1}(z)=\varphi(z)-\sum_{j=1}^{2} \sum_{k=0}^{\infty} \alpha_{k j}^{* *}\left(\frac{R}{z-b_{j}}\right)^{k+1}  \tag{3}\\
& \psi_{1}(z)=\psi(z)-\sum_{j=1}^{2} \sum_{k=0}^{\infty} \beta_{k j}^{(2)}\left(\frac{R}{z-b_{j}}\right)^{k+1} \\
& \alpha_{0 j}^{* *}=\alpha_{0 j}-h_{2} R, \quad \beta_{n j}^{* *}=2 \beta_{0 j} ; \quad \alpha_{i j j}^{* *}=\alpha_{k j}, \quad \beta_{k j}^{* *}=\beta_{k j}, \quad k \geqslant 1 \\
& \beta_{0 j}^{(2)}=\beta_{0 j}^{* *}, \quad \beta_{k j}^{(2)}=\bar{\beta}_{k j}^{* *}-k \frac{b_{j}}{R} \alpha_{k-1, j}^{* *}+(k-1) \alpha_{k-2, j}^{* *}, \quad k \geqslant 1
\end{align*}
$$

Taking into account what has been said so far, we put ( $\alpha_{k j}{ }^{*}$ and $\beta_{k j}^{*}$ are real quantities)

$$
\begin{aligned}
& \alpha_{k j}^{* *}=\alpha_{k j}{ }^{*}, \quad \beta_{k j}{ }^{* *}=\beta_{k j}^{*}, \quad k=0,2,4, \ldots \\
& \alpha_{k j}^{* *}=i \alpha_{k j}^{*}, \quad \beta_{k j}{ }^{* *}=i \beta_{k j}^{*}, \quad k=1,3,5, \ldots
\end{aligned}
$$

Using relations (3) we can [1-3] reduce the solution of the problem in question to a solution of an intermediate problem for the region $S$. The boundary conditions for the last problem are:

$$
\begin{align*}
& Y_{k}^{(2)}-i X_{y}^{(2)}=-\sum_{j=1}^{2} \sum_{k=0}^{\infty} \frac{k+1}{R}\left\{\alpha_{k j}^{* *}\left(\frac{R}{t-b_{j}}\right)^{k+2}+\gamma_{k j}^{* *}\left(\frac{R}{\overline{t-b_{j}}}\right)^{k+2}-(4)\right.  \tag{4}\\
& \left.\quad(k+2) \bar{\alpha}_{k j}^{* *} \frac{t}{R}\left(\frac{R}{\overline{t-b_{j}}}\right)^{k+3}\right\}, \quad t=x \pm i a \\
& \gamma_{0 j}^{* *}=\bar{\alpha}_{0 j}^{* *}+\beta_{n j}^{* *}, \quad \gamma_{k j}^{* *}=\bar{\alpha}_{k j}^{* *}+k \frac{b_{j}}{R} \bar{\alpha}_{k-1, j}^{* *}+(k-1) \bar{\alpha}_{k-2, j}^{* *}+\beta_{k j}^{* *}, \quad k \geq 1
\end{align*}
$$

and the solution obtained using the integral Founier transforms, has the form

$$
\left.\begin{array}{c}
\varphi(z)=-i \int_{-\infty}^{\infty} H_{1}(\mu) e^{-i z \mu / a} \frac{d \mu}{\mu} \\
\psi(z)=i \int_{-\infty}^{\infty}\left[\left(1-i z \frac{\mu}{a}\right) H_{1}(\mu)+2 H_{2}(\mu)\right] e^{-i z \mu / a} \frac{d \mu}{\mu} \\
H_{1}(\mu)=\sum_{j=0}^{\infty} T_{j}(\mu)\left\{\left[\left(a_{j}(\mu)+2 \gamma(\mu)\right) \Gamma_{1_{1}, j}(\mu)+2 \varepsilon_{2} \mu \Gamma_{3, j}(\mu)\right] \alpha_{j}^{*}-\Gamma_{2, j}(\mu) \beta_{j}^{*}\right\} \\
H_{2}(\mu)=\sum_{j=0}^{\infty} T_{j}(\mu)\left\{\left[\left(2 \mu^{2}-a_{j}(\mu) b(\mu)\right) \Gamma_{1, j}(\mu)-2 \varepsilon_{2} \mu b(\mu) \Gamma_{3_{j} j}(\mu) \mid \alpha_{j}^{*}+\right.\right. \\
\left.b(\mu) \Gamma_{2, j}(\mu) \beta_{j}^{*}\right\}, \quad T_{j}(\mu)=\frac{\varepsilon_{1}^{j+1}}{i!} \frac{\mu^{j+1}}{2 \mu+\operatorname{sh} 2 \mu} \\
\Gamma_{1, j}(\mu) \\
\Gamma_{2, j}(\mu)
\end{array}\right\}=\cos j \frac{\pi}{2} \operatorname{ch} \varepsilon_{2} \mu \pm \sin j \frac{\pi}{2} \operatorname{sh} \varepsilon_{2} \mu, \quad \alpha_{j}(\mu)=j+\frac{\left(\varepsilon_{1} \mu\right)^{2}}{j+2} .
$$

$$
\begin{aligned}
& \Gamma_{3 . j}(\mu)=\sin j \frac{\pi}{2} \operatorname{ch} \varepsilon_{2} \mu+\cos j \frac{\pi}{2} \operatorname{sh} \varepsilon_{2} \mu, \quad b(\mu)=1-\gamma(\mu) \\
& 2 \gamma(\mu)=1-2 \mu+e^{-2 \mu}, \quad \varepsilon_{1}=R / a, \quad \varepsilon_{2}=c / a
\end{aligned}
$$

It should be noted that $H_{1}(\mu)$ and $H_{2}(\mu)$ are symmetric functions, and the expressions given here are for $\mu>0$ only.

The only unknown quantities left are $\alpha_{j}{ }^{*} \equiv \alpha_{j 1}{ }^{*}$ and $\quad \beta_{j}{ }^{*} \equiv \beta_{j 1}{ }^{*}$. To find them, we require an infinite system of linear algebraic equations. This can be constructed e.g. by first obtaining [1] an integral equation (for $\omega(t)$ ) with a degenerate kernel

$$
\begin{equation*}
\omega(t)=\varphi(t)-\overline{t \varphi^{\prime}(t)}-\overline{\psi(t)}+\sum_{k=0}^{\infty}\left[\Omega_{k}^{(1)}\left(\frac{t-b_{1}}{R}\right)^{k}+\Omega_{k}^{(2)}\left(\frac{R}{t-b_{1}}\right)^{k}\right]+ \tag{6}
\end{equation*}
$$

$$
\alpha_{-1,1} \text { on } L_{1}
$$

$$
\Omega_{1}^{(1)}=\frac{\beta_{0}^{*}}{2}, \quad \Omega_{k}^{(1)}=(-1)^{k+1} \sum_{n=0}^{\infty} \bar{\alpha}_{n, 1}^{* *} C_{n+k}^{k}\left(\frac{\varepsilon_{2}}{2 i}\right)^{n+k+1}, \quad k \neq 1
$$

$$
\Omega_{k}^{(2)}=\delta_{k} h_{2} R+\sum_{n=0}^{\infty}(-1)^{n+1}\left(\frac{\varepsilon_{3}}{2 i}\right)^{n+k+1}\left\{( n + 1 ) a _ { n , 1 } ^ { * * } \left[C_{n+k+1}^{k}-\right.\right.
$$

$$
\left.\left.\left(\frac{\varepsilon_{3}}{2}\right)^{2} C_{n+k+3}^{k+1}\right]+\bar{\beta}_{n, 1}^{* *} C_{n+k}^{k}\right\}
$$

$$
C_{m}^{n}=\frac{m!}{n!(m-n)!}, \quad \varepsilon_{3}=\frac{R}{c} ; \quad \delta_{1}=1, \quad \delta_{k}=0, \quad k \neq 1
$$

The functions $\varphi(t)$ and $\psi(t)$ can be found using formulas (5). Solving the integral equation (6), we arrive at the required system

$$
\begin{gathered}
\sum_{j=1}^{\infty} a_{k j} x_{j}=g_{k}, \quad k=1,2,3, \ldots \\
x_{2 j+1}=\alpha_{j}^{*}, \quad x_{2 j+2}=\beta_{j} * ; \quad g_{1}=-2 h_{2} R, \quad g_{2}=-h_{1} R, \quad g_{k}=0, \quad k \geqslant 3
\end{gathered}
$$

and we write the coefficients $a_{n j}$ as follows ( $\delta_{i, j}$ is the Kronecker delta)

$$
\begin{gather*}
a_{2 m+1,2 n+1}=\delta_{2 m+1,2 n+1}-\int_{0}^{\infty} T_{m n}(\mu)\left\{\Gamma _ { m n } ^ { 1 1 } ( \mu ) \left[4 \mu^{2}+2 \gamma(\mu)\left(2+a_{m}(\mu)+(8)\right.\right.\right.  \tag{8}\\
\left.\left.a_{n}(\mu)\right)+a_{m}(\mu) a_{n}(\mu)\right]+2 \varepsilon_{2} \mu\left[f_{m}(\mu) \Gamma_{m n}^{13}(\mu)+f_{n}(\mu) \Gamma_{m n}^{s 1}(\mu)\right]+ \\
\left.4 \varepsilon_{2}{ }^{2} \mu^{2} \Gamma_{m n}^{s 3}(\mu)\right\} d \mu+(n+1) \varepsilon_{m n} K(m, n)\left[C_{m+n+2}^{m+1}-\left(\frac{\varepsilon_{3}}{2}\right)^{2} C_{m+n+4}^{m+2}\right] \\
a_{2 m+2,2 n+2}= \\
a_{n+1}^{(1)} \delta_{2 m+2,2 n+2}-\int_{0}^{\infty} T_{m n}(\mu) \Gamma_{m n}^{22}(\mu) d \mu \\
a_{2 m+1,2 n+2}=\int_{0}^{\infty} T_{m n}(\mu)\left[f_{m}(\mu) \Gamma_{m n}^{12}(\mu)+2 \varepsilon_{2} \mu \Gamma_{m n}^{s 2}(\mu)\right] d \mu+\tau_{m n} K(m,-n) \\
a_{2 m+2,2 n+1}=\int_{0}^{\infty} T_{m n}(\mu)\left[f_{n}(\mu) \Gamma_{m n}^{21}(\mu)+2 \varepsilon_{2} \mu \Gamma_{m n}^{23}(\mu)\right] d \mu+\tau_{m n} K(-m, n)
\end{gather*}
$$

$$
\begin{aligned}
& T_{m n}(\mu)=\frac{2 e_{1}^{m+n+2}}{(m+1)!n!} \frac{\mu^{m+n+1}}{2 \mu+s h 2 \mu} \\
& K(m, n)=\cos (m-n) \frac{\pi}{2}-\sin (m+n) \frac{\pi}{2} \\
& \Gamma_{m n}{ }^{i j}(\mu)=\Gamma_{i, m}(\mu) \Gamma_{j, n}(\mu), \quad \varepsilon_{m n}=\left(\varepsilon_{y} / 2\right)^{m+n+2} \\
& f_{j}(\mu)=2 \gamma(\mu)+a_{j}(\mu), \quad \tau_{m n n}=\varepsilon_{m n} C_{m+n+1}^{m} \\
& \delta_{1}{ }^{(1)}=1 / 2, \quad \delta_{k}(1)=1, \quad k \geqslant 2 ; \quad m, n=0,1,2, \ldots
\end{aligned}
$$

Relations (8) yield the following expressions which reduce considerably the amount of numerical computations required:

$$
\frac{a_{\alpha, \beta}}{a_{\beta, \alpha}}=\frac{n+1}{m+1} ; \quad \alpha=2 m+1, \quad 2 m+2 ; \quad \beta=2 n+1, \quad 2 n+2
$$

Analysing the expressions (8) we find, that the syatem (7) is at least quasiregular at arbitrarily close distances from the boundary. Solving the system (7) and then computing the stresses with help of the known [4] formulas, we complete the investigation of the problem formulated above.

Numerical analysis, some results of which are quoted below, was carried out for $\varepsilon_{1}=0.1,0.2,0.3,0.4,0.45$ and $\varepsilon_{2}=\left(1+\varepsilon_{1}\right) / 3$ (in the latter case all three necks have the same width. We recall that $\varepsilon_{1}$ and $\varepsilon_{2}$ are the ratios of the hole radius and the half-distance between the hole centers respectively, to the half-width of the strip). The computations were carried out for three cases of strip loading given at the beginning of this paper. The infinite system (7) was truncated, for the given values of $\varepsilon_{1}$, to $14,18,26,34$ and 40 equations. The longitudinal boundary conditions were satisfied in all cases practically $100 \%$. The absolute error in the woas case of $\mathrm{s}_{1}=0.45$ was of the order of $10^{-6}$. At the hole contours the boundary conditions were also satisfied to high order of accuracy, the error in the worst case of $\varepsilon_{1}=$ 0.45 being equal to $0.57 \%$.

All computations were carried out in the first quadrant, and some of the results are given in tables. The upper line in each pair of values corresponds to the case of a strip stretched in the longitudinal direction by the force $T_{x}=$ const, and the lower line to the stretching by the force $T_{y}=$ const. Multiplying the relevant values by $T_{x}$ or $T_{y}$ as appropriate, gives the actual values of the stresses. The Tables can also be used to obtain the corresponding stresses for a strip subjected to a uniform load $P$ along the hole contours. In this case both numbers are added together, the sum reduced by 1 , and the result multiplied by $P$.

Table 1 gives the stresses $\sigma_{\theta}$ along the hole contouns (angle $\theta$ is counted from the point $A$ in the direction $A B C$ ).

The stress $J_{\theta}$ at the hole contours was computed using a $15^{\circ}$ step. Table 1 quotes the values for a $30^{\circ}$ step, and this means that some of the extremal values (from the computations using a narrower step) are missing. We give them here: for
$T_{y}=0, \varepsilon_{1}=0.4, \theta=105^{\circ}: \sigma_{\theta}=-1.8489 T_{x}, \quad$ for $\quad T_{x}=0, \varepsilon_{1}=0.3, \theta=$ $105^{\circ}: \sigma_{\theta}=3.8030 T_{y}$ and for $T_{x}=0, \varepsilon_{1}=0.45, \theta=135^{\circ}: \sigma_{\theta}=8.7166 T_{y}$.

Table 2 gives the values of the stress $X_{x}{ }^{(1)}$ along the vertical symmetry axis. The points are sampled in the direction $O A C D$, using a step $(c-R) / 3$ on the

Table1

| $\mathbf{t}_{2}$ | $\theta^{\circ}=0$ | 30 | 60 | 90 | 120 | 150 | 180 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0.1 | 3.068 | 2.079 | 0.054 | -1.006 | $-0.011$ | 2.054 | 3.098 |
|  | -0.960 | $-0.021$ | 1.941 | 3.006 | 2.051 | 0.010 | -1.029 |
| 0.2 | 3.313 | 2.412 | 0.219 | -1.108 | -0.160 | 2.196 | 3.503 |
|  | -0.816 | $-0.205$ | 1.745 | 3.181 | 2.401 | 0.082 | -1.255 |
| 0.3 | 4.193 | 3.138 | 0.411 | -1.331 | -0.588 | 2.333 | 4.600 |
|  | -0.832 | -0.652 | 1.528 | 3.610 | 3.321 | 0.490 | -1.956 |
| 0.4 | 7.967 | 4.507 | 0.625 | -1.610 | -1.558 | 1.812 | 8.146 |
|  | -2.175 | -1.404 | 1.293 | 4.250 | 5.399 | 2.927 | $-4.223$ |
| 0.45 | 16.076 | 5.815 | 0.777 | -1.735 | -2.409 | -0.244 | 15.052 |
|  | -5.524 | -2.143 | 1.110 | 4.608 | 7.281 | 8.475 | -8.418 |

Table 2

| $E_{1}$ | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0.1 | 1.115 | 1.143 | 1.307 | 3.068 | 3.098 | 1.117 | 1.038 | 0.953 |
|  | 0.046 | 0.048 | 0.026 | -0.960 | -1.029 | 0.048 | 0.058 | 0.161 |
| 0.2 | 1.600 | 1.568 | 1.298 | 3.313 | 3.503 | 1.521 | 1.176 | 0.821 |
|  | -0.001 | -0.085 | -0.195 | $-0.816$ | -1.255 | 0.045 | 0.263 | 0.703 |
|  | 2.893 | 3.007 | 3.390 | 4.193 | 4.600 | 2.405 | 1.529 | 0.639 |
| 0.3 | -0.428 | -0.470 | -0.603 | -0.831 | -1.955 | -0.074 | 0.770 | 1.945 |
|  | 6.875 | 6.984 | 7.329 | 7.967 | 8.146 | 4.873 | 2.658 | 0.432 |
| 0.4 | -1.880 | $-1.910$ | -2.004 | -2.177 | -4.222 | $-0.370$ | 2.478 | 5.729 |
|  | 14.981 | 15.094 | 15.443 | 16.076 | 15.052 | 9.506 | 4.907 | 0.295 |
| 0.45 | -5.141 | $-5.179$ | -5.295 | -5.497 | -8.371 | $-0.666$ | 6.093 | 13.291 |

Table 3

| $t_{1}$ | 1 | 2 | 3 | 4 | 5 | 6 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0.1 | 0.196 | $-0.072$ | $-0.007$ | 0.007 | 0.006 | 0.003 |
|  | 0.685 | 1.094 | 1.029 | 1.001 | 0.996 | 0.997 |
| 0.2 | 0.524 | -0.229 | -0.036 | 0.022 | 0.020 | 0.011 |
|  | 0.134 | 1.284 | 1.118 | 1.008 | 0.986 | 0.988 |
| 0.3 | 0.649 | -0.346 | -0.110 | 0.035 | 0.039 | 0.022 |
|  | -0.151 | 1.384 | 1.287 | 1.032 | 0.973 | 0.975 |
| 0.4 | 0.571 | -0.279 | -0.247 | 0.031 | 0.058 | 0.034 |
|  | -0.158 | 1.184 | 1.558 | 1.095 | 0.964 | 0.959 |
| 0.45 | $0.569$ | -0.143 | -0.337 | 0.012 | 0.062 | 0.038 |
|  | -0.201 | 0.916 | 1.728 | 1.157 | 0.969 | 0.953 |

segment $O A$ (point 1-4) and a step $2(\mathrm{c}-R) / 3$ on the segment $C D$ (points $5-8$ ).
Table 3 contains the stresses $Y_{y}{ }^{(1)}$ along the horizontal symmetry axis. The points are sampled beginning from the coordinate origin, in the positive direction of the $x$ axis, using a step of 0.4 a .

The stresses at the points belonging to the longitudinal boundaries were computed using a step of 0.3 a for all given values of $\varepsilon_{1}$. The values obtained for the stresses $X_{i}{ }^{(1)}$ and $Y_{y}{ }^{(1)}$ were used to draw conclusions about the accuracy with which the boundary conditions were satisfied. The stress $X_{x}{ }^{(1)}$ itself is of particular interest. When $T_{x}=$ const $\neq 0, T_{!/}=0, \varepsilon_{1}=0.45$, the stress varies at the points indicated (with the accuracy of up to the factor $r_{x}$ ) as follows: it attains a minimum of 0.2951 at the point $D$, is equal to 7.0142 at the point $x=0.3 a$, and from then on it diminishes in value and tends to unity ( $X_{x}{ }^{(1)}=1.0109 T_{x}$ at $\left.x=2.1 a\right)$.

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